

| | Ref # | Hits | Search Text | DBs | Time Stamp |
|-----|-------|-------|---|---|---------------------|
| 8 | S8 | 1425 | vehicle\$1 near3 (driving near2 (behavior or dynamic\$1 or situation\$1)) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 13:57 |
| 9 | S9 | 36248 | vehicle\$1 near3 (dynamic\$1 or behavior\$1 or characteristic\$1 or handling) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 13:58 |
| 10 | S10 | 78 | (corner\$3 near2 stiff\$4) near5 (vehicle\$1 or wheel\$1) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 13:59 |
| 11 | S11 | 73871 | (load\$1 or force\$1) near3 (wheel\$1 or tire\$1 or tyre\$1) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 13:59 |
| 12 | S12 | 26304 | ((load\$1 or force\$1) near3 (appl\$4 or act\$3 or exert\$3)) near5 (wheel\$1 or tire\$1 or tyre\$1) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 14:00 |
| 13 | S13 | 3255 | ((load\$1 or force\$1) near3 (vertical or longitudinal)) near5 (wheel\$1 or tire\$1 or tyre\$1) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 14:01 |
| 14 | S14 | 3919 | ((load\$1 or force\$1) near3 (lateral or transverse)) near5 (wheel\$1 or tire\$1 or tyre\$1) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 14:01 |
| 15 | S15 | 161 | (corner\$3 near3 stiffness) near5 (wheel\$1 or tire\$1 or tyre\$1) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 14:02 |
| 16 | S16 | 1015 | (model\$1 or observer\$1 or state\$ near2 (unit or device) or state near2 variable\$1) near10 (vehicle\$1 near3 (dynamic\$1 or behavior or characteristic\$1)) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 14:04 |
| 17 | S17 | 31956 | (model\$1 or observer\$1 or state\$ near2 (unit or device)) near10 (equation\$1 or variable\$1) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 14:05 |
| 18 | S18 | 1218 | (tire\$1 or tyre\$1 or wheel\$1) near5 (slip near3 angle\$1) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 14:05 |
| 19 | S19 | 50 | ((tire\$1 or tyre\$1 or wheel\$1) near5 (slip near3 angle\$1)) near10 (driving near2 situation\$1 or vehicle near2 (dynamic\$1 or behavior)) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 14:07 |
| 20. | S20 | 853 | ((state\$1 or space) near3 (model or observer) or state\$1 near2 variable\$1 or model or observer) near10 (vehicle near3 (characteristic\$1 or behavior or dynamic\$1)) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | 2006/01/19 14:09 |